

**What is...quantum topology - part 21?**

---

Or: Pivotal categories 3 from Chapter 4

## Swapping factors

$$\text{X} : \bullet^2 \rightarrow \bullet^2$$

$$\text{X} = |, |, \text{X} =$$

- ▶ Say we have some set  $\bullet$ ; consider  $\bullet^d = \bullet \times \dots \times \bullet$
- ▶ Take the swap map:  $\bullet^2 \rightarrow \bullet^2, (x, y) \mapsto (y, x)$
- ▶ Above The diagrammatic algebra of the swap map which investigate soon!

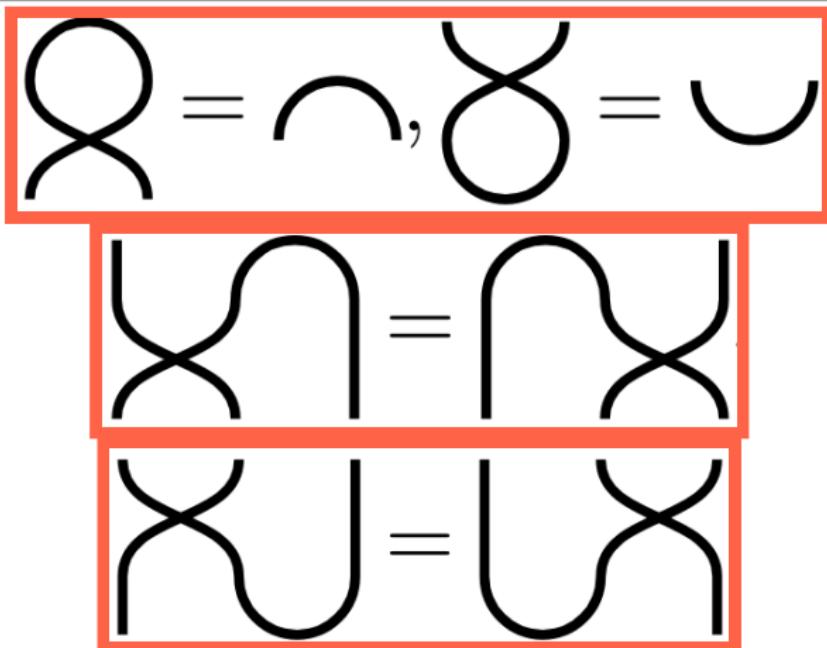
## Pairing factors

$$\text{Diagram: } \bullet^2 \rightarrow \mathbb{1}, \text{Diagram: } \mathbb{1} \rightarrow \bullet^2$$

$$\text{Diagram: } \bullet^2 \rightarrow \mathbb{1} = \mathbb{1} \rightarrow \bullet^2$$

- ▶ Say we have some  $\mathbb{C} = \mathbb{1}$  vector space  $\bullet$ ; consider  $\bullet^d = \bullet \otimes \dots \otimes \bullet$
- ▶ Take a (nondegenerate symmetric) **pairing map**  $\bullet^2 \rightarrow \mathbb{1}, x \otimes y \mapsto \langle x, y \rangle$  (identify  $\bullet$  with its dual); take the **copairing**  $\mathbb{1} \rightarrow \bullet^2, 1 \mapsto \sum_{\text{basis}} x \otimes x^*$
- ▶ Above The diagrammatic algebra of the (co)pairing maps (rigid/pivotal)

## Swapping and pairing



- ▶ Say we have some  $\mathbb{C} = \mathbb{1}$  vector space  $\bullet$ ; consider  $\bullet^d = \bullet \otimes \dots \otimes \bullet$
- ▶ Take swapping and pairing together
- ▶ Above The diagrammatic algebra of the swapping and (co)pairing maps  $Br$

## For completeness: A formal statement

**Br** gives diagrammatics of orthogonal  $O_n(\mathbb{C})$  or symplectic  $SP_n(\mathbb{C})$  invariants

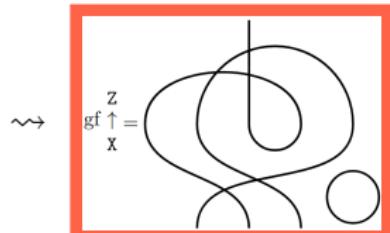
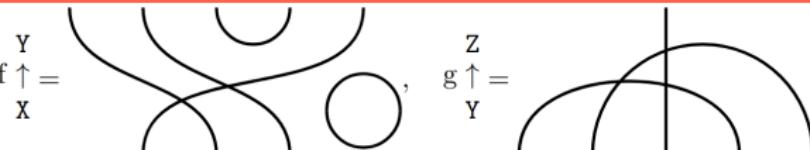
ON ALGEBRAS WHICH ARE CONNECTED WITH THE SEMISIMPLE  
CONTINUOUS GROUPS\*

BY RICHARD BRAUER

(Received March 5, 1937)

1. **Introduction.** We consider a group  $\mathfrak{G}$  of linear transformations in an  $n$ -dimensional vector space  $V_n$ . If a transformation  $G$  of  $\mathfrak{G}$  is performed, the components of a general tensor of rank  $f$  undergo a linear transformation  $M_f(G)$  and these  $M_f(G)$  form a representation  $\mathfrak{M}_f$  of  $\mathfrak{G}$ . The investigation of  $\mathfrak{M}_f$  is of great importance for the theory of representations. In particular, we have to study the breaking up of  $\mathfrak{M}_f$  into its irreducible constituents. When dealing with this question we may replace  $\mathfrak{M}_f$  by its enveloping algebra  $A_f$ , i.e. the totality of all matrices which can be written as linear combinations of matrices of  $\mathfrak{M}_f$  with scalar coefficients.

- ▶ **Formally** There is a “full and essentially surjective” functor  $\mathbf{Br} \rightarrow \mathbf{Rep}(O)$  or  $\mathbf{Rep}(SP)$ , and the “kernel” can also be described
- ▶ **Comment**  $GL_n(\mathbb{C})$  does not have a natural pairing, hence  $O_n(\mathbb{C})$ ,  $SP_n(\mathbb{C})$
- ▶ We have seen this in more generality (up to the swap)!





# Pivot Point

[*'pi-vət 'pōint*]

A technical analysis indicator, or calculations, used to determine the overall trend of the market over different time frames.

- ▶ Diagrammatic algebra seems to originate in 19th century invariant theory
- ▶ Pivotal comes from pivot = 'rotation point'
- ▶ Rigid is an older name and I do not know where it comes from

**Thank you for your attention!**

---

I hope that was of some help.