

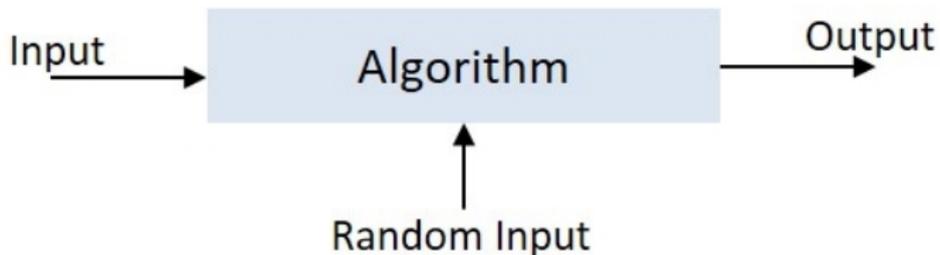
What are...randomized algorithms?

Or: Randomness rocks!

Algorithm + random = ?



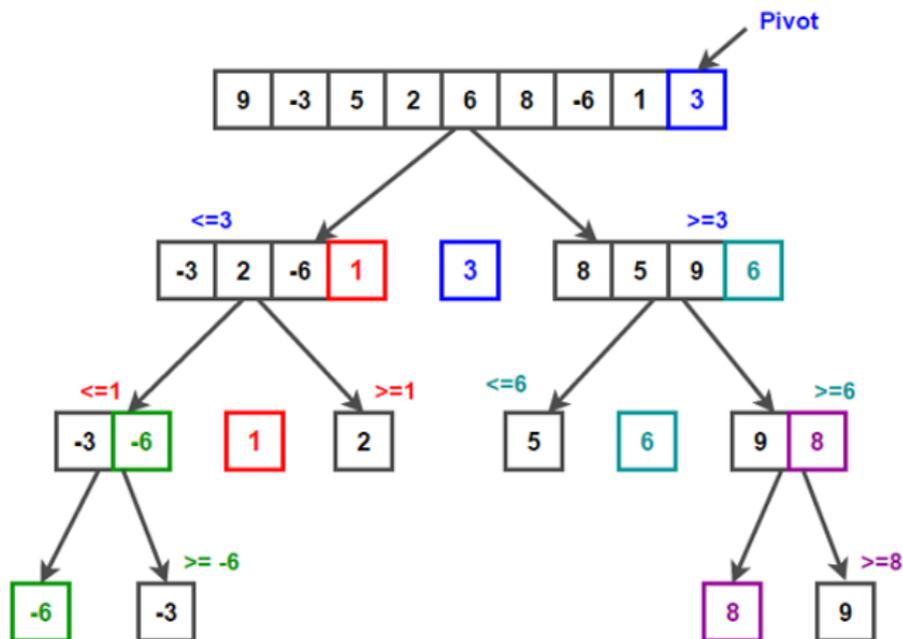
(a) Deterministic algorithm structure



(b) Randomized algorithm structure

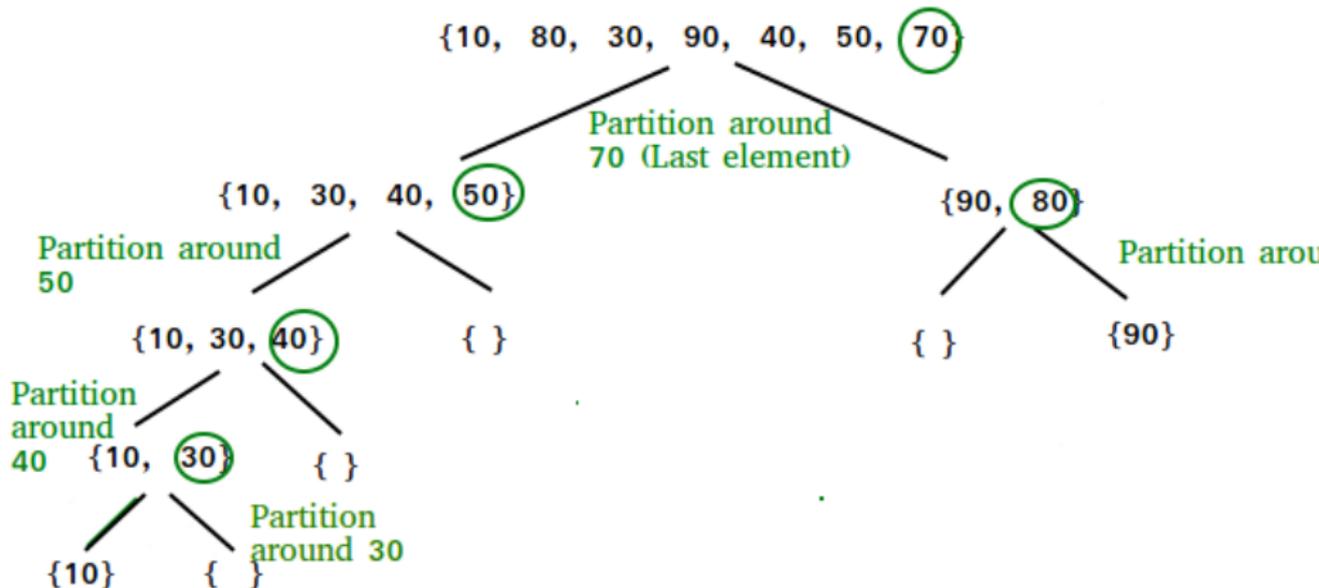
- ▶ **Algorithm** A deterministic procedure
- ▶ **Random** The opposite ;-)
- ▶ **Randomized algorithm** A degree of randomness in a deterministic procedure

Quicksort



- ▶ **Goal** Sort a set X
- ▶ Take a pivot p and divide into $X(< p)$ and $X(\geq p)$ **Divide**
- ▶ Repeat with $X(< p)$ and $X(\geq p)$ **Conquer**

Pick a random pivot



- ▶ Best/worst case scenario Divide into two equally sized sets resp. as above
- ▶ Idea: Choose a pivot randomly!
- ▶ In this way one ends in the average situation most of the time

Enter, the theorem

Take a set X with n elements

The expected-case resp. worst-case time of randomized quicksort is

$$O(n \log n) \text{ resp. } O(n^2)$$

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- ▶ The average-case resp. worst-case time of plain quicksort is

$$O(n \log n) \text{ resp. } O(n^2)$$

⇒ good average-case performance but not good worst-case performance

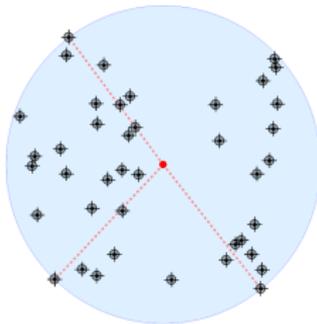
- ▶ The difference?

(a) Average = on random input

(b) Expected = on every input with large probability

- ▶ Making the algorithm probabilistic gives more control over the running time
- ▶ Randomizing algorithms works way more general than for quicksort

The smallest-circle problem



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algorithm welzl is
  input: Finite sets  $P$  and  $R$  of points in the plane  $|R| \leq 3$ .
  output: Minimal disk enclosing  $P$  with  $R$  on the boundary.

  if  $P$  is empty or  $|R| = 3$  then
    return trivial( $R$ )
  choose  $p$  in  $P$  (randomly and uniformly)
   $D := \text{welzl}(P - \{p\}, R)$ 
  if  $p$  is in  $D$  then
    return  $D$ 

  return welzl( $P - \{p\}, R \cup \{p\}$ )
```

- ▶ Goal Find the smallest circle surrounding given points X
- ▶ Take randomly p and find the smallest circle for $X \setminus \{p\}$ recursively
- ▶ The expect run time is $O(n)$

Thank you for your attention!

I hope that was of some help.