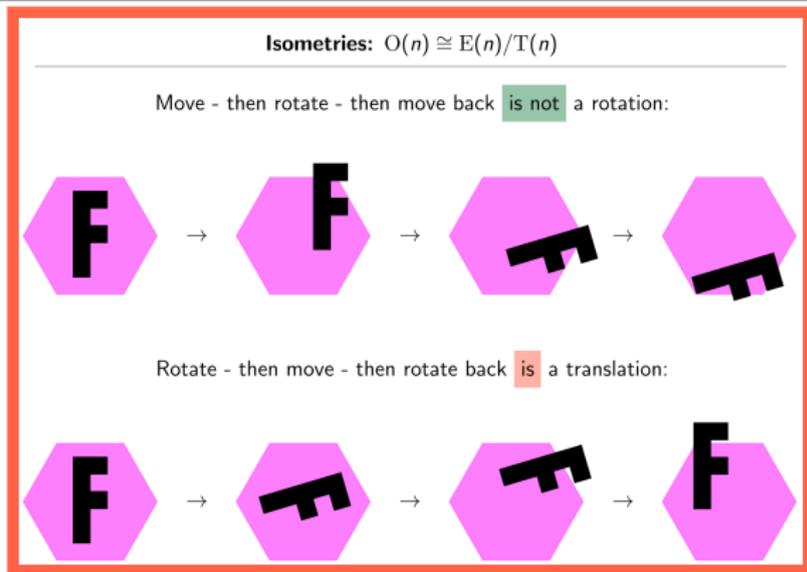


Lie theory - part 9

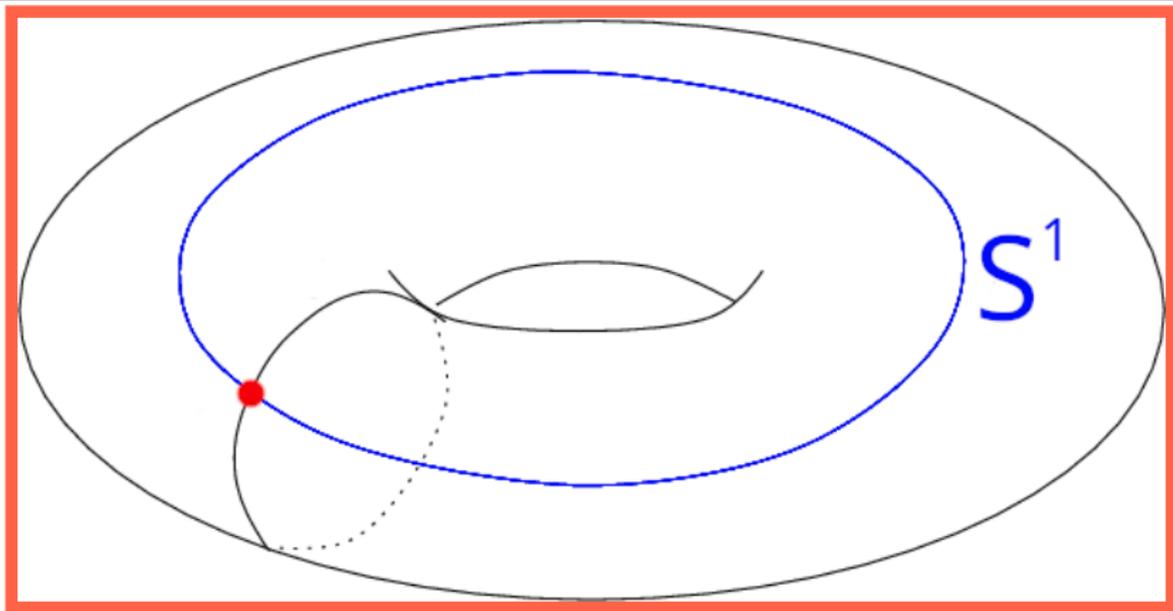
Or: Ideals and quotient Lie algebras

Ideals: the subalgebras you can safely “mod out”



- ▶ **Definition** An ideal $\mathfrak{a} \triangleleft \mathfrak{g}$ satisfies $[X, A] \in \mathfrak{a}$ for all $X \in \mathfrak{g}$, $A \in \mathfrak{a}$
- ▶ **Symmetry meaning** \mathfrak{a} is a “direction” that the whole algebra can push you into, but you never leave
- ▶ **Analogy** Ideals are the Lie algebra version of normal subgroups (the ones compatible with quotients)

First (non-)examples

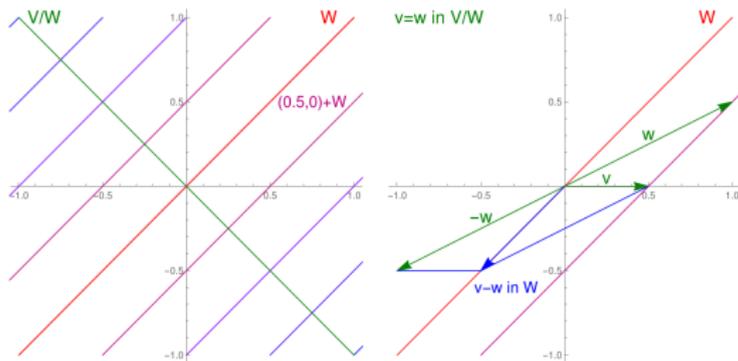


- ▶ Always $\{0\}$ and \mathfrak{g} are ideals; $\ker(\varphi)$ is an ideal for any homomorphism φ
- ▶ Matrix example In \mathfrak{gl}_n , scalar matrices form a central ideal (they commute with everything)
- ▶ Non-example In \mathfrak{gl}_2 , the subalgebra $\mathfrak{k} = \left\{ \begin{pmatrix} a & 0 \\ 0 & 0 \end{pmatrix} : a \in \mathbb{C} \right\}$ is not an ideal

Quotients: collapsing “invisible” directions

Linear identification along codim 1

What happens if we collapse a line $W = \mathbb{R}(1, 1)$ in $V = \mathbb{R}^2$ to a point?



The lines parallel to W are the points of V/W , $\dim V/W = 1$

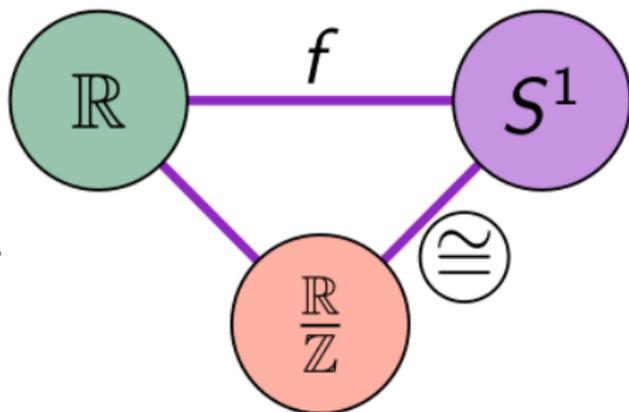
- ▶ **Vector spaces** The quotient $\mathfrak{g}/\mathfrak{a}$ identifies elements differing by things in \mathfrak{a}
- ▶ **Bracket on cosets** Define $[X + \mathfrak{a}, Y + \mathfrak{a}] = [X, Y] + \mathfrak{a}$
- ▶ **Why ideals** This is well-defined exactly because \mathfrak{a} is stable under bracketing with all of \mathfrak{g}

The first isomorphism theorem (Lie version)

$$\frac{\mathbb{R}}{\mathbb{Z}} \cong S^1 = \text{Circle}$$

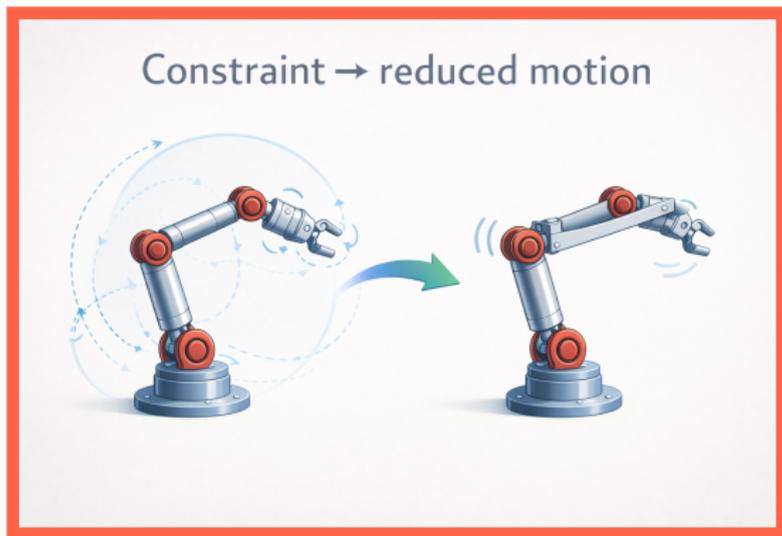
$$\exp(2\pi i _): \mathbb{R} \rightarrow S^1$$

\mathbb{Z} kernel of f



- ▶ **Statement** If $\varphi : \mathfrak{g} \rightarrow \mathfrak{h}$ is a homomorphism, then $\mathfrak{g}/\ker(\varphi) \cong \text{im}(\varphi)$
- ▶ **Meaning** “Forget what φ kills” and you get exactly the symmetry you can actually see in the target
- ▶ **Use** This is the basic tool for simplifying Lie algebras by factoring out redundant directions

Back to symmetries: constraints and reduction



- ▶ **Constraints** Often you impose relations that declare some motions “invisible”
 \Rightarrow quotient by an ideal
- ▶ **Reduction** You keep the symmetry information that still acts nontrivially after the constraint
- ▶ **Preview** Next: simple/semisimple Lie algebras = those with no nontrivial solvable ideals (structure theory begins)

Thank you for your attention!

Next time: The centre, derived algebra, and “simple” vs “solvable”